TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

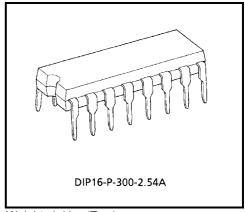
TA8415P

STEPPING MOTOR CONTROLLER / DRIVER

The TA8415P is general purpose unipolar stepping motor controller / driver, applicable to 3 / 4 phase motors and 1, 1–2, 2 phase excitation drive by initial setting of control terminals.

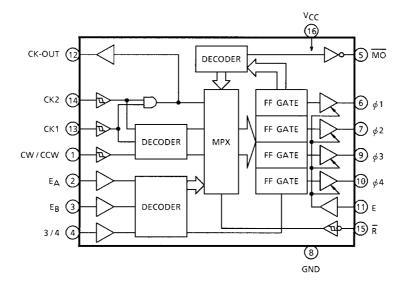
FEATURES

- 1 chip stepping motor controller / driver.
- 3 or 4 phase and 1, 1–2, 2 phase excitation drive are available.
- CW / CCW rotation and 1 clock or 2 clock drive are available.
- Hysteresis is provided with clock, CW / CCW, reset inputs for noise protection.
- Output enable, initial detect are available.
- Output current up to 400mA (MAX.)



Weight: 1.11 g (Typ.)

BLOCK DIAGRAM



PIN FUNCTION

PIN No.	SYMBOL	PIN NAME	FUNCTIONAL	. DESCRIPTION	
1	CW / CCW	Clock Wise / Counter Clock Wise	Direction Control Input Function Table A		
2	E _A	Excitation A	Phase Excitation Mode		
3	E _B	Excitation B	Input	Truth Table B	
4	3 / 4	3 Phases / 4 Phases	Phase Control Input		
5	MO	Monitor Out	MO = "L" at Initial State		
6	φ1	φ1 Out	φ1 Output		
7	φ2	φ2 Out	φ2 Output		
8	GND	GND	GND		
9	φ3	φ3 Out	φ3 Output		
10	φ4	φ4 Out	φ4 Output		
11	Е	Output Enable	Outputs are Enable at E =	"H"	
12	CK-OUT	Clock-Out	Clock Output		
13	CK1	Clock I _n -1	Clock Input 1	- Truth Table A	
14	CK2	Clock I _n -2	Clock Input 2	- Hulli Table A	
15	R	Reset	Reset Input		
16	V _{CC}	V _{CC}	V _{CC}		

TRUTH TABLE A

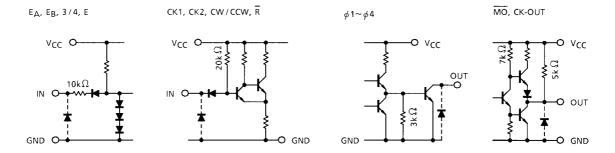
CK1	CK2	CW / CCW	FUNCTION
4	Н	L	CW
닠	L	L	Inhibit
Н	Կ	Ш	CCW
L	5	L	Inhibit
님	Н	Н	CCW
닉	L	Н	Inhibit
Н	4	Н	CW
L		Н	Inhibit

TRUTH TABLE B

E _A	E _B	3 / 4 (Note)		FUNCTION				
L	L	L		1 Phase Excitation				
Н	L	L	4 Phases	2 Phase Excitation				
L	Н	L		1-2 Phase Excitation				
Н	Н	L	Test Mode φ1~φ4 ON					
L	L	Н		1 Phase Excitation				
Н	L	Н	3 Phases	2 Phase Excitation				
L	Н	Н		1-2 Phase Excitation				
Н	Н	Н	Test Mode φ1~φ4 ON					

Note: Conversion of Phase Excitation Mode must be made after the Reset Mode is established.

SCHEMATIC OF INPUTS AND OUTPUTS



MAXIMUM RATINGS (Ta = 25°C Unless otherwise noted)

CHARACTERISTIC	SYMBOL	RATING	UNIT	
Supply Voltage	V _{CC}	-0.3~7.0	V	
Output Sustaining Voltage	V _{CE} (SUS) φ	-0.3~28	V	
Output Current (φn)	Ι _{ΟUΤ} φ	400	mA	
Output Current (MO, CK-OUT)	I _{OUT} MO CK-OUT	10	mA	
Input Voltage	V _{IN}	-0.3~V _{CC} + 0.3	V	
Input Current	I _{IN}	±1	mA	
Power Dissipation	PD	1.2	W	
Operating Temperature	T _{opr}	-30~85	°C	
Storage Temperature	T _{stg}	-55~150	°C	

RECOMMENDED OPERATION CONDITION (Ta = $-30 \sim 85$ °C)

CHARACTER	RISTIC	SYMBOL	TEST CONDITION	MIN	TYP.	MAX	UNIT	
Supply Voltage		V _{CC}	_	4.5	5.0	5.5	V	
Output Sustaining Volta	ge	V _{CE (SUS)} φ	_	0	_	26	V	
Output Current φn	"L" Level	Ι _{ΟυΤ} φ	_	_	_	200	mA	
Output Current MO,	"H" Level	I _{OH}	_	_	_	-0.4	mA	
CK-OUT	"L" Level	I _{OL}	_	_	_	8		
Input Voltage		V _{IN}	_	0	_	V _{CC}	V	
Clock Frequency		fclock	_	0	_	100	kHz	
Power Dissipation		P _D	_	_	_	0.6	W	

ELECTRICAL CHARACTERISTICS (Ta = 25°C)

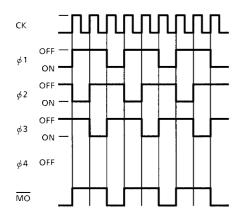
CHARACTERISTIC		SYMBOL	TEST CIR- CUIT	TEST CONDITION	MIN	TYP.	MAX	UNIT	
		Level	V _{IH}		_	2.0	_	_	V
Input Voltage		evel	V _{IL}	_	_	_	_	0.8	\ \ \
Input Current		Level	I _{IH}		V _{CC} = 5.5 V, V _{IH} = 5.5 V	_	_	10	μΑ
input Current		_evel	I _{IL}		V _{CC} = 5.5 V, V _{IL} = 0.4 V	_	_		mA
Hysteresis	<u> </u>		ΔV_{T}	_	_	_	150	_	mV
Supply Curre	Supply Current		I _{CC}	_	_	_	_	100	mA
Output Leaka	age Current	φn	Іонф	_	V _{CC} = 5.5 V, V _{OUT} = 26 V	_	_	100	μΑ
	"H" Level	MO	V		V _{CC} = 4.5 V, I _{OH} = -0.4 mA	2.4	_	_	
	n Level	CK-OUT	V _{OH}	_	V _{CC} = 5.0 V, I _{OH} = -10 μA	4.0	_	_	
Output		MO CK-OUT	V _{OL}	_	V _{CC} = 4.5 V, I _{OL} = 8 mA	_	_	0.4	V
Voltage	"L" Level	ru Level φn V _{OUT} φ —	_	V _{CC} = 4.5 V, I _{OUT} = 400 mA t = 100 ms	_	_	1.1		
			_	V _{CC} = 4.5 V, I _{OUT} = 200 mA t = 100 ms	_	_	0.6		

SWITCHING CHARACTERISTICS (Ta = 25°C)

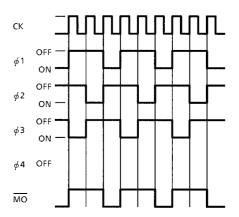
CH.	CHARACTERISTIC		SYMBOL	TEST CIR- CUIT	TEST CONDITION	MIN	TYP.	MAX	UNIT
		CK-φn				_	2.0	_	
		CK-CK-OUT				_	1.0	_	
	"H" Level	CK-MO	t_{pLH}		_	_	2.8	_	
		E-φn				_	1.0	_	
Propa-		R-φn				_	2.0	_	
gation Delay Time		CK-φn			_	_	1.4	_	μs
rime	"L" Level	CK-CK-OUT	^t pHL	_		_	0.7	_	
		CK-MO				_	2.1	_	
		E-φn				_	1.2	_	
		_ R -φn				_	1.0	_	
		R-MO				_	2.0	_	
Maximum Clo	ck Frequer	псу	f _{max}	_	_	_	250	_	kHz
Set Up Time CK, CW / CCW		t _{set-up}	_	_	_	0.1	_		
Hold Time CK, CW / CCW		t _{hold}	_	_	_	0.1	_		
Minimum Clock Pulse Width		t _{w (CK)}	_	_	_	1.0	_		
Minimum Reset Pulse Width		t _{w (R)}	_	_	_	1.0	_		
Maximum Clo	ck Rise Tin	ne	t _r (CK)	_	_	_	10	_	μs

TIMING CHART 3 PHASES METHOD

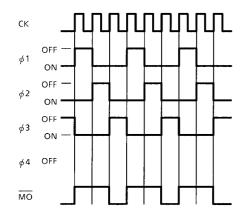
1 PHASE EXCITATION CW



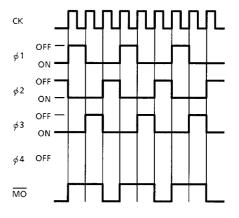
1 PHASE EXCITATION CCW



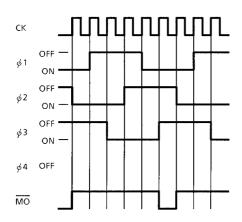
2 PHASE EXCITATION CW



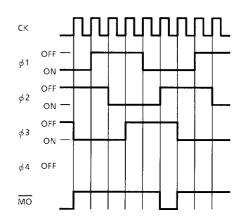
2 PHASE EXCITATION CCW



1-2 PHASE EXCITATION CW

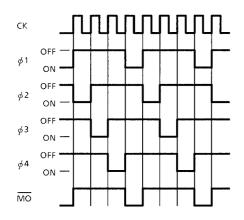


1-2 PHASE EXCITATION CCW

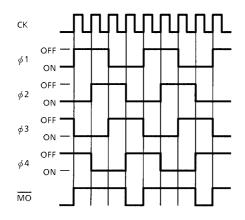


4 PHASES METHOD

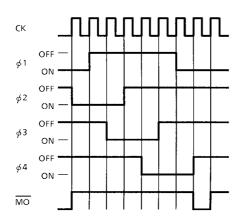
1 PHASE EXCITATION CW



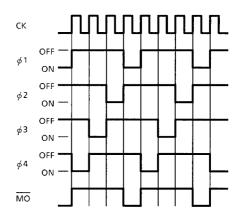
2 PHASE EXCITATION CW



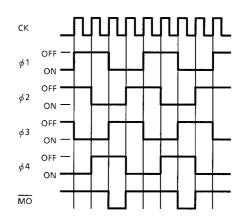
1-2 PHASE EXCITATION CW



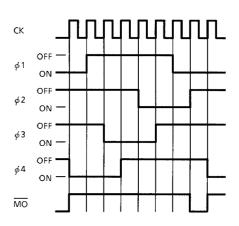
1 PHASE EXCITATION CCW

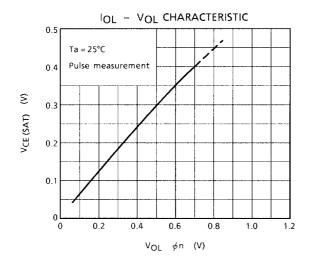


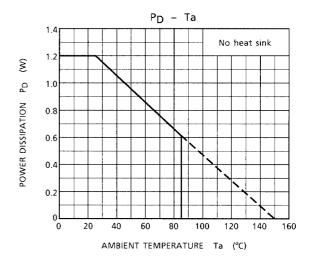
2 PHASE EXCITATION CCW



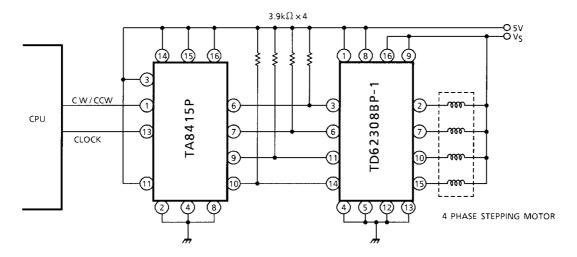
1-2 PHASE EXCITATION CCW



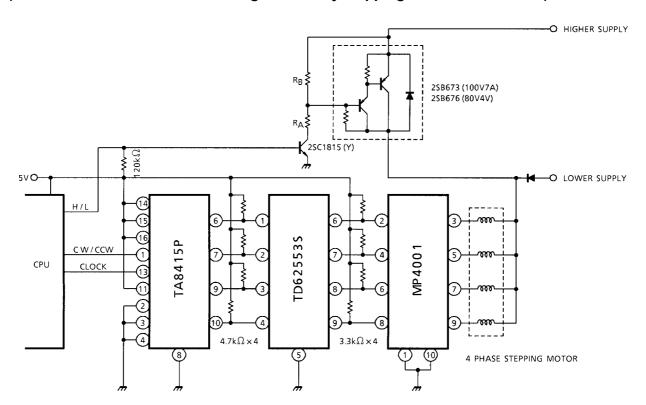




APPLICATION CIRCUIT 1 (TA8415P + TD62308BP 4 phase stepping motor driver circuit)

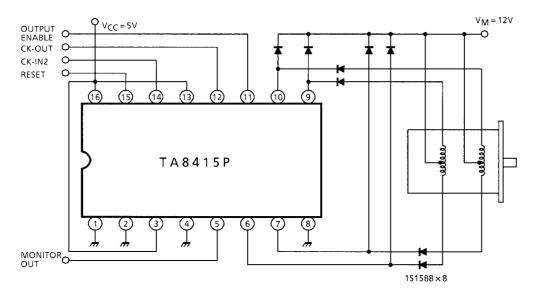


APPLICATION CIRCUIT 2 (TA8415P + TD62553S + MP4001 high efficiency stepping motor driver circuit)



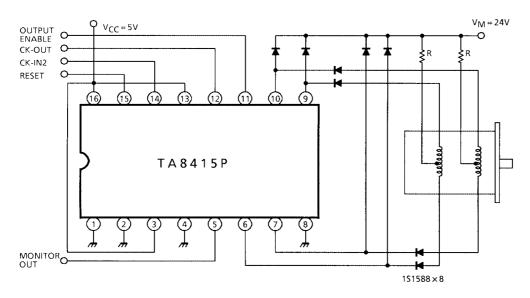
APPLICATION CIRCUIT 3

4 phase motor 1–2 phase excitation drive I.



APPLICATION CIRCUIT 4

4 phase motor 1-2 phase excitation drive II.



Note: Utmost care is necessary in the design of the output line, power supply and GND line since IC may be destroyed due to short-circuit between outputs, air contamination fault, or fault by improper grounding.

PACKAGE DIMENSIONS

DIP16-P-300-2.54A

Unit: mm

19.75MAX

19.25±0.2

0.735TYP

1.4±0.1

0.5±0.1

0.5±0.1

0.5±0.1

0.0.25 (M)

Weight: 1.11 g (Typ.)

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